

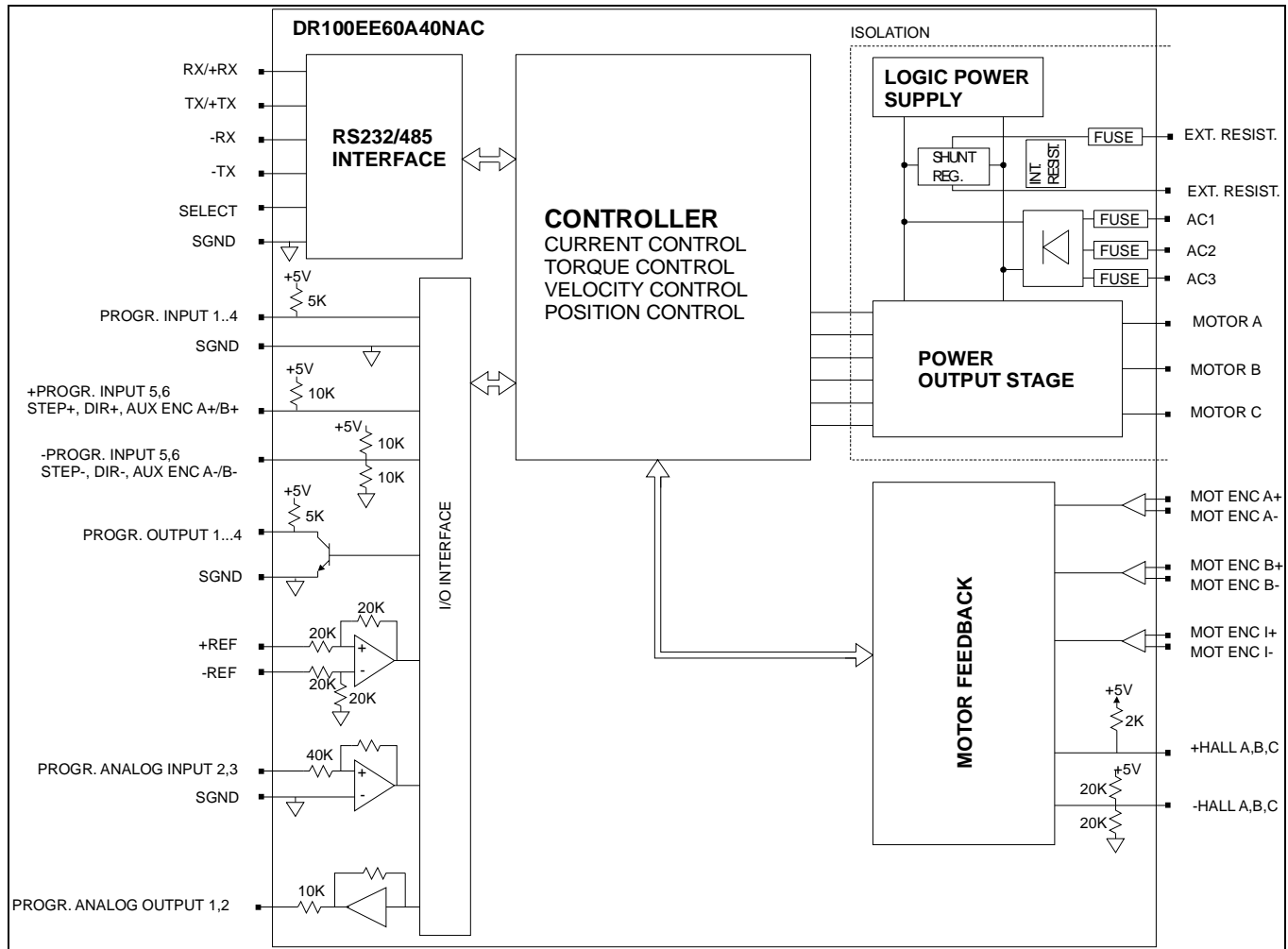
DIGIFLEX® DIGITAL SERVO DRIVES MODEL: DR100EE60A40NAC

FEATURES:

- Fully digital, state-of-the-art design
 - Space Vector Modulation and vector control technology
 - 20kHz Digital current loop with programmable gain settings
 - PIDF velocity loop with 100microsecond update rate
 - PID + FF position loop with 100 microsecond update rate
 - Hall sensor + encoder or encoder-only based commutation
 - Surface-mount technology
 - Small size, low cost, ease of use
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- RS232/485 interface for setup and networking
 - Windows© based setup software with built-in 8-channel digital scope
 - Operates in torque, velocity or position mode with programmable gain settings
 - Programmable profiling in all modes
 - Fully configurable current, voltage, velocity and position limits.
 - Step & direction mode for stepper replacement
 - Encoder following with programmable gear ratio
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- 4 programmable digital inputs
 - 2 programmable differential inputs, configurable as step & direction, master encoder, or secondary encoder for dual loop operation
 - 4 programmable digital outputs
 - 2 programmable analog inputs (10-bit)
 - 14-bit reference input or programmable analog input
 - 2 programmable analog outputs (10-bit)
 - Encoder output (from motor, optionally buffered)
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- Off-line 1 or 3-phase 240VAC operation
 - Four quadrant regenerative operation
 - Integrated shunt regulator and resistor
 - Provision for external shunt resistor
 - Bi-color LED status indicator
 - Extensive built-in protection against:
 - over-voltage (programmable)
 - under-voltage (programmable)
 - short-circuit: phase-phase, phase-ground
 - over-current
 - over-temperature



BLOCK DIAGRAM:



DESCRIPTION:

The DR100EE Series digital PWM servo drives are designed to drive brushed and brushless servomotors. These fully digital drives can operate in torque, velocity, or position mode and employ Space Vector Modulation (SVM), which results in higher bus voltage utilization and reduced heat dissipation. The command source can be generated internally or can be supplied externally. In addition to motor control, these drives feature dedicated and programmable digital and analog inputs and outputs to enhance interfacing with external controllers and devices.

DR100EE Series drives feature a single RS232/485 interface, which is used for drive configuration and setup as well as online operation in networked applications. Drive commissioning can be accomplished through a fully graphical Windows© based application.

All drive and motor parameters are stored in non-volatile memory.

SPECIFICATIONS:

POWER STAGE SPECIFICATIONS	DR100EE60A40NAC
AC SUPPLY VOLTAGE	40 – 270 VAC, 1 or 3-phase, 50 – 60 Hz
PEAK CURRENT	60A (42.4 Arms)
MAXIMUM CONTINUOUS CURRENT	30A (21.2 Arms)
MINIMUM LOAD INDUCTANCE	600 µH
SWITCHING FREQUENCY	20 kHz
HEATSINK (BASEPLATE) TEMPERATURE RANGE	0 to 65 °C, disables at 65 °C
POWER DISSIPATION AT CONTINUOUS CURRENT	400W
MIN. UNDER-VOLTAGE SHUTDOWN	55 VDC
MAX. OVER-VOLTAGE SHUTDOWN	439 VDC
BUS CAPACITANCE	1650 µF
SHUNT RESISTOR	20Ω, 100W internal
SHUNT SWITCH-ON VOLTAGE	Programmable
SHUNT FUSE	5A Motor Delay @ 250VAC
AC LINE FUSING	3 x 20A @ 600VAC

MECHANICAL SPECIFICATIONS	
AC SUPPLY CONNECTOR: C1	Screw terminal
SHUNT AND DC OUT CONNECTOR: C2	Screw terminal
MOTOR POWER CONNECTOR: P1	Screw terminal
MOTOR FEEDBACK CONNECTOR: CN3*	15-pin high density female D-sub
I/O CONNECTOR: CN2*	26-pin high density female D-sub
COMMUNICATIONS INTERFACE (RS232/485): CN1*	9-pin female D-sub
SIZE	9.24 x 6.37 x 5.96 inches 234.7 x 161.8 x 151.3 mm
WEIGHT	

* Mating connectors are not included.

PIN FUNCTIONS:

C1 – AC Supply Connector:

CONNECTOR	PIN	NAME	DESCRIPTION	I/O
C1	1	AC1	AC supply input. 40 – 270 VAC, 3-phase.	I
	2	AC2		I
	3	AC3		I
	4	CASE GND	Case ground	GND
	5	NC	Not connected	-

C2 – Shunt and DC Out Connector:

CONNECTOR	PIN	NAME	DESCRIPTION	I/O
C2	1	HV	DC bus output	O
	2	PGND	DC bus ground	PGND
	3	EXT. SHT	External shunt resistor	O
	4	EXT SHT.	External shunt resistor	O
	5	INT. SHT. Jumper	Jumper to C2-4 for internal shunt resistor. Remove for external shunt.	-

P1 - Motor Power Connector:

CONNECTOR	PIN	NAME	DESCRIPTION	I/O
P1	1	MA	Motor phase A	O
	2	MB	Motor phase B	O
	3	MC	Motor phase C	O
	4	PGND	DC bus ground	PGND
	5	HV	DC bus output	O

CN3 - Motor Feedback Connector:

CONNECTOR	PIN	NAME	DESCRIPTION	I/O
CN3	1	+Hall A	Commutation sensor inputs. Internal 2K pull-up to +5VDC. Can be used with single ended or differential Hall sensors.	I
	2	+Hall B		I
	3	+Hall C		I
	4	MOT ENC A+	Differential Encoder Input. For single ended encoder signals, leave the A-terminal open.	I
	5	MOT ENC A-		I
	6	MOT ENC B+	Differential Encoder Input. For single ended encoder signals, leave the B-terminal open.	I
	7	MOT ENC B-		I
	8	MOT ENC I+	Differential Encoder Input. For single	I

9	MOT ENC I-	ended encoder signals, leave the I-terminal open.	I
10	-Hall A*	See CN3-1. Leave open in case of single ended Hall sensors.	I
11	-Hall B*	See CN3-2. Leave open in case of single ended Hall sensors.	I
12	SGND	Signal ground	SGND
13	+5V OUT	+5V @ 250mA max. Short-circuit protected.	O
14	PAI3	Programmable analog input, single ended, 10-bit	I
15	-Hall C*	See CN3-3. Leave open in case of single ended Hall sensors.	I

* Contact factory for SE compatible options.

CN2 – I/O Connector:

CONNECTOR	PIN	NAME	DESCRIPTION	I/O
CN2	1	PDO1*	Programmable digital output	O
	2	SGND	Signal ground	SGND
	3	PDO2*	Programmable digital output	O
	4	+REF	Differential reference signal input, 14-bit resolution. Can also be used as programmable analog input 1.	I
	5	-REF		I
	6	PAI2	Programmable analog input	I
	7	PAO1	Programmable analog output	O
	8	PAO2	Programmable analog output	O
	9	-PDI6	Programmable Input (see CN2-18) or Direction- or Aux Enc B-	I
	10	PDO3	Programmable digital output	O
	11	PDI1	Programmable digital input	I
	12	PDI2	Programmable digital input	I
	13	PDI3	Programmable digital input	I
	14	PDO4	Programmable digital output	O
	15	+5V OUT	+5VDC. Note: the total current on CN2-15 and CN3-13 combined should not exceed 250 mA	O
	16	SGND	Signal ground	SGND
	17	+PDI5	Programmable differential digital input, or Step+ or Aux Enc A+	I
	18	+PDI6	Programmable, differential digital input or Direction+ or Aux Enc B+	I
	19	PDI4	Programmable digital input	I
	20	Encoder Channel A+	Encoder Output (from connector CN3), not buffered	O
	21	Encoder Channel A-		O
	22	Encoder Channel B+	Encoder Output (from connector CN3), not buffered	O
	23	Encoder Channel B-		O

	24	Encoder Channel I+	Encoder Output (from connector CN3), not buffered	O
	25	Encoder Channel I-		O
	26	-PDI5	Programmable Input (See CN2-17) or Step- or Aux Enc A-	I

* Contact factory for SE compatible options.

CN1 - Communications Interface (RS232/485):

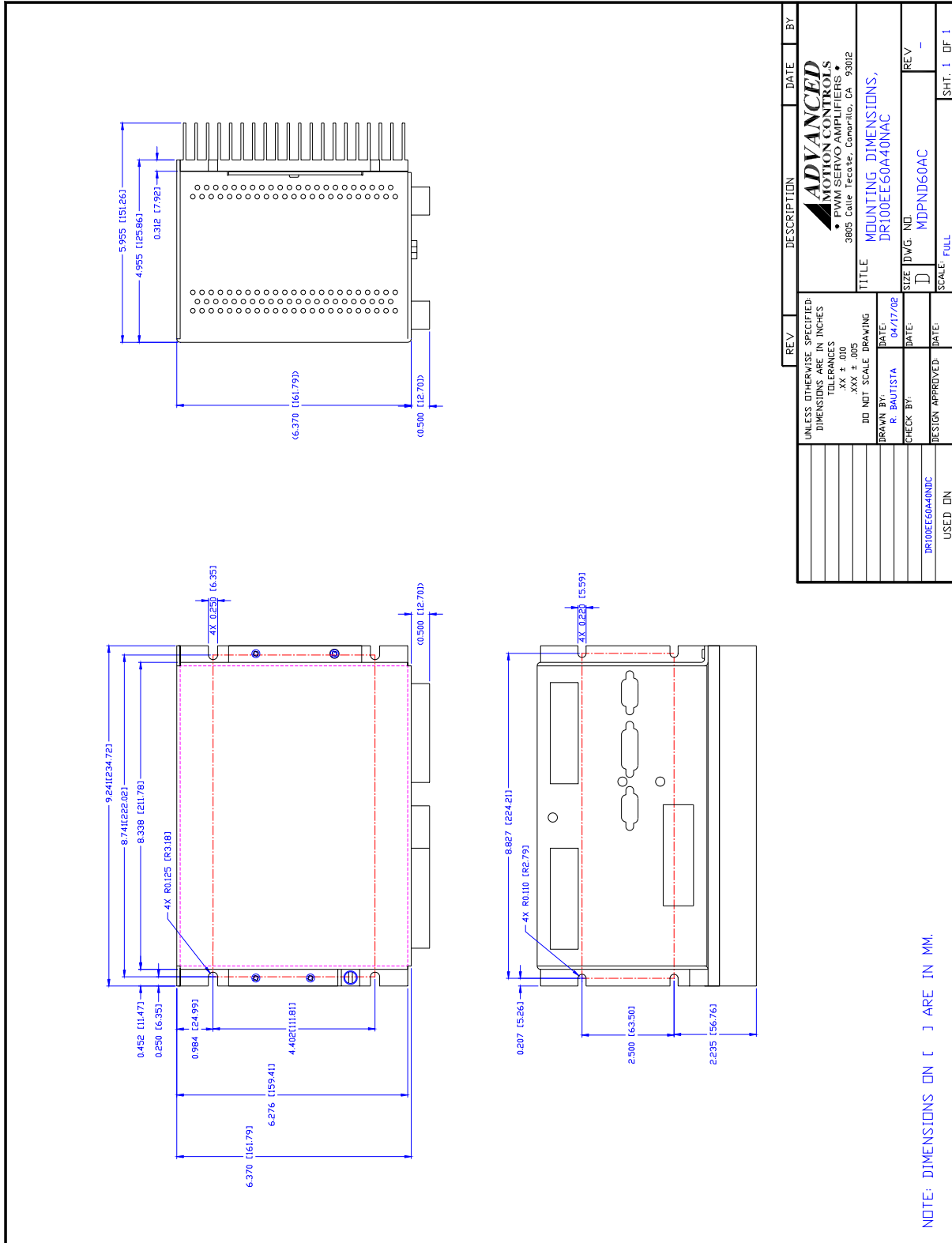
CONNECTOR	PIN	NAME	DESCRIPTION	I/O
CN1	1	SELECT	RS232/485 selection. Pull to ground (CN1-5) for RS485.	I
	2	TX/+TX	RS232: Transmit; RS485: +TX	O
	3	RX/+RX	RS232: Receive; RS485: +RX	I
	4	N/C	Not connected	
	5	SGND	Signal ground	SGND
	6	-TX	RS485: -TX	O
	7	N/C	Not connected	
	8	-RX	RS485: -RX	I
	9	N/C	Not connected	

ORDERING INFORMATION:

Standard model: DR100EE60A40NACX

X indicates the current revision letter.

MOUNTING DIMENSIONS:



NOTE: DIMENSIONS ON [] ARE IN MM.

REV	DESCRIPTION	DATE	BY
	UNLESS OTHERWISE SPECIFIED: DIMENSIONS ARE IN INCHES TOLERANCES ARE: FRACTIONS XXX ± .005 DO NOT SCALE DRAWING		
	DRAWN BY: R. BOUTISTA	DATE: 04/17/08	
	CHECK BY:	DATE:	
	DESIGN APPROVED:	DATE:	
	USED ON: DR100EE60A40NC		
		SCALE: FULL	
		SIZE DWG. NO.:	REV
		MDPND60AC	-
		TITLE: MOUNTING DIMENSIONS, DR100EE60A40NAC	SHT. 1 OF 1
		ADVANCED MOTION CONTROLS • PWM SERVO AMPLIFIERS • 3805 Calle Tecate, Camarillo, CA 93012	